## Sun Woo Kim

**Email**: ska503@sfu.ca **Homepage**: https://pulsekim.github.io/

**Research Interests** 

Character animation with both physics-based and kinematics-based

• Deep reinforcement learning for motion control of characters and robots

• Text to motion retrieval and generation

• Body gesture generation for multimodal conversational agents

Education

**Simon Fraser University** 

British Columbia, Canada

Ph.D. Student in Computing Science

Sep 2025 - Present

Supervisor: Jason Peng

Research Topic: Human motion generation using reinforcement learning

**Seoul National University** 

Seoul, Korea

Master's degree in Computer Science

Sep 2019 – Sep 2022

Supervisor: Jehee Lee, Sehoon Ha

Research Topic: Human motion control of quadrupedal robots

Pohang University of Science and Technology

Pohang, Korea

Bachelor's degree in Creative IT Engineering

Feb 2015 - Feb 2019

Magna cumme laude GPA: 3.88 / 4.3

Work Experience

NC AI (Spun offed from NCSOFT)

Sungnam, Korea

AI Researcher, Motion Service Lab

Feb 2025 - Sep 2025

Research Topic: Text to motion retrieval & genertaion

**NCSOFT** 

Sungnam, Korea

AI Researcher, Graphics AI Lab

Aug 2022 - Feb 2025

Research Topic: Gesture generation

**Publications** 

Conferences

**Body Gesture Generation for Multimodal Conversational Agents** 

Sunwoo Kim, Minwook Chang, Yoonhee Kim, Jehee Lee

SIGGRAPH Asia, 2024.

Towards Natural Prosthetic Hand Gestures: A Common-Rig and Diffusion Inpainting Pipeline

Seungyup Ka, Taemoon Jeong, <u>Sunwoo Kim</u>, Sankalp Yamsani, Joohyung

Kim, Sungjoon Choi

IEEE Engineering in Medicine and Biology Society (EMBC), 2024.

Human Motion Control of Quadrupedal Robots using Deep RL	<b>Human Motion</b>	Control	of Quadrup	edal Robots	using Deep RI
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Sunwoo Kim, Maksim Sorokin, Jehee Lee, Sehoon Ha

Robotics: Science and Systems (RSS), 2022.

### **Journals**

### **Controllable Single Motion Synthesis**

Taehyun Byun, **Sunwoo Kim**, Minwook Chang, Sungjoon Choi (Submitted)

### Workshops

# HumanConQuad: Human Motion Control of Quadrupedal Robots using Deep RL

<u>Sunwoo Kim</u>, Maksim Sorokin, Jehee Lee, Sehoon Ha

Emerging Technologies, SIGGRAPH Asia, 2022.

Awards & Scholarships

Special Grad Entrance Scholarship (Computing Science Dept, SFU) 2025

Master's Award: 2nd prize (Korea Computer Graphics Society) 2022

Human Motion Control of Quadrupedal Robots using Deep RL

Grand prize (Ministry of Science and ICT, Korea) 2018

Improved Color Palette Extraction from Pictures (present 4:12, awarded 1:38:00)

Grand prize (POSTECH) 2017

Creative Design III: Improved Color Palette Extraction from Pictures

Grand prize (POSTECH) 2016

Creative Design II: Artistic Video Transfer using Deep Learning

**Teaching Experience** 

Teaching assistant, Seoul National University

Spring 2021

Core Computing: Computation thinking (Dr. Jehee Lee)

Undergraduate tutor, POSTECH

Spring 2018

Introduction to Digital System & Microprocessor Design (Dr. Jaejoon Kim)

**Professional Service** 

### Paper Reviewer

SIGGRAPH, SIGGRAPH Asia

Other Experience

**Booth Staff**, NC AI exhibition booth at SIGGRAPH

2025

Assisted in presenting research and interacting with attendees.

References

### Prof. Xue Bin (Jason) Peng

Assistant Professor, Simon Fraser University Research Scientist, NVIDIA xbpeng@sfu.ca

### Prof. Jehee Lee

Professor, Seoul National University jeheel@snu.ac.kr

### Prof. Sehoon Ha

 $Assistant\ Professor,\ Georgia\ Institute\ of\ Technology\\ sehoonha@gatech.edu$